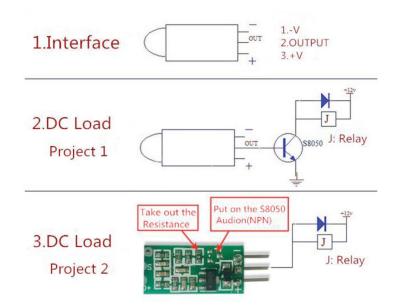
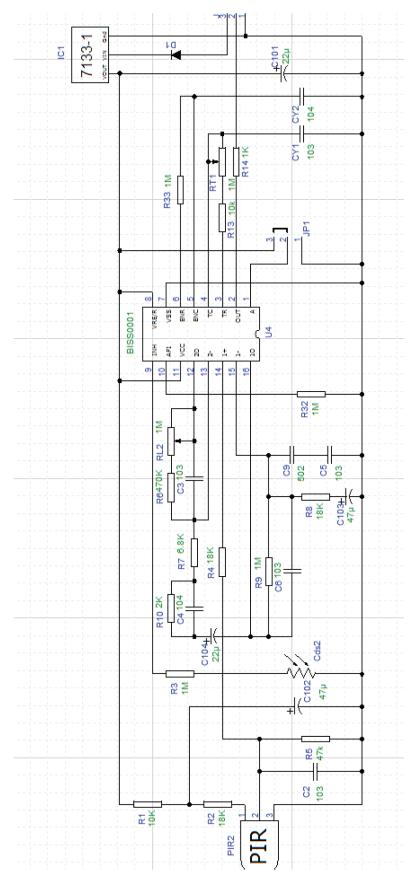


Product Specification

Operating voltage range: DC4.5-20V Quiescent Current: <60uA Level output: High 3.3V / Low OV Trigger: reusable trigger (default) Delay Time: The default 8S + -30% Board Dimensions: 10 * 23mm Induction angle: <100 degrees cone angle Sensing distance: 3 meters Working temperature: -20 to +80 degrees Sensor Lens Dimensions: Diameter 10mm

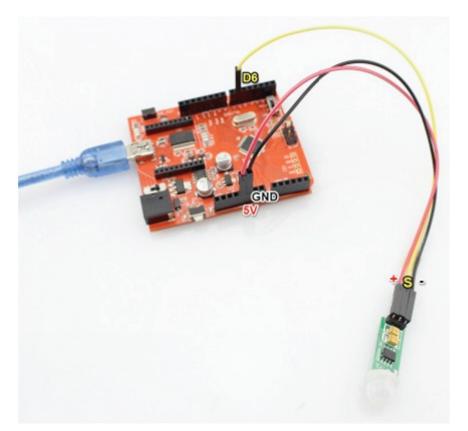




SCHEMATIC

Hardware

Connect the PIR Motion Sensor to your Arduino/Crowduino power supply pin and digital pins. You can can connect the "s" terminal to any of your arduino Pins, like the "D6" as belows:



Programming

1. Copy the following program to Arduino IDE and upload to your Arduino/Crowduino:

```
void setup() {
   Serial.begin(9600);
   pinMode(6,INPUT);
   digitalWrite(6,LOW);
}
void loop() {
    if(digitalRead(6)==HIGH) {
      Serial.println("Somebody is here.");
   }
   else {
      Serial.println("Nobody.");
   }
   delay(1000);
}
```

2. Open the Serial moniter, and set the baudrate to 9600, you will see that When somebody is in front of the sensor, the Serial Monitor will output "Somebody is here." Or, the Serial Monitor output "Nobody."

5 COM33	
	Send
Nobody.	-
Nobody.	
Nobody.	
Nobody.	
Nobody.	=
Nobody.	
Nobody.	
Somebody is here.	
	+
🔽 Autoscroll Newline	